

# Quantitative network design for biosphere model process parameters



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## Background and Motivation

Current uncertainty about the present and future behaviour of the terrestrial **carbon cycle** has stimulated the research community to build appropriate observing networks. **Quantitative network design**, based on **inverse modelling** systems aims to optimize such networks.

This approach is used, in the framework of the **European project IMECC** (Infrastructure for Measurement of the European Carbon Cycle), to evaluate candidates of networks that better constrain the process parameters of a biospheric model. The impact of various atmospheric and terrestrial measurements on the uncertainty of process parameters and concomitant uncertainty of calculated fluxes is demonstrated, along with a tool for assessing networks.

## Methodology

### Carbon Cycle Data Assimilation System

The network design tool is based on the CCDAS (Carbon Cycle Data Assimilation System) (Figure 1). The system consists of the terrestrial biosphere model BETHY (Biosphere Energy Transfer Hydrology) (Knorr, 2000), which can couple with several atmospheric transport models (e.g., Scholze, 2003, Rayner et al., 2005).

CCDAS allows the calculation of diagnostic (Rayner et al., 2005) and prognostic (Scholze et al., 2007) quantities.

### Formalism of the network design tool

The method is based on the assessment of candidate networks of carbon cycle measurements through the computation of the uncertainty on a target quantity (Kaminski and Rayner, 2008). The method solves an inverse problem, which is formulated as a minimization of a cost function  $J(x)$ :

$$J(x) = \frac{1}{2} \left[ \sum_{i=1}^n \frac{1}{(\sigma_{d_i})^2} (M_i(x) - d_i)^2 + (x - x_0)^T \cdot C(x_0)^{-1} \cdot (x - x_0) \right]$$

$x$ : parameters to be optimized with prior values  $x_0$  and uncertainty  $C(x_0)$

$d$ : the observations

$\sigma_{d_i}$ : the uncertainty in observations and model

$M(x)$ : the model  $M$  result corresponding to the observations  $d$

$(.)^T$  denotes the transposed

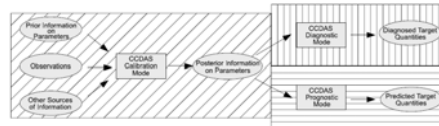
### Uncertainty on a target quantity

If the model  $M$  is linear, the data  $d$  and the priors of the parameters  $x$  have a Gaussian Probability Density Function (PDF), then the posterior (i.e., optimized) values of  $x$  also have a Gaussian PDF (Tarantola, 1987). The posterior uncertainty  $C(x_{op})$  is given by the inverse of the Hessian  $H$  (i.e., the second derivative) of the cost function  $J(x)$  (equation 1). Following Rayner et al., 2005, the uncertainty  $C(y)$  of a target quantity  $y(x)$  is approximated to first order by the equation (2).

$$C(y) \approx \frac{dy}{dx}(x_{op}) \cdot C(x_{op}) \cdot \frac{dy}{dx}(x_{op})^T$$

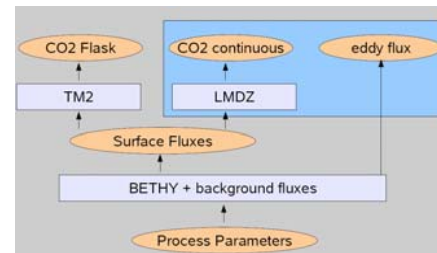
$C(x_{op}) \approx H^{-1}$ .  $H$  is the Hessian of the cost function defined by

$$H = \frac{d^2 J(x_{op})}{dx^2} = \frac{1}{2} \sum_{i=1}^n \frac{1}{(\sigma_{d_i})^2} \frac{d^2}{dx^2} (M_i(x) - d_i)^2 + C(x_0)^{-1}$$



**Figure 1:** The two-steps procedure for inferring diagnostic and prognostic target quantities from CCDAS.

- Rectangular boxes: processes.
- Oval boxes: data
- Diagonally hatched box: inversion or calibration step.
- Vertical hatched box: diagnostic step.
- Horizontally hatched box: prognostic step.



**Figure 2:** Carbon Cycle Assimilation System (CCDAS). Forward modelling chain together with the modules for full network design tool.

## Set up

The network designer allows to handle (Figure 2):

- Flask sampling of atmospheric  $CO_2$ , using the transport model TM2 as observational operator.
- Continuous samples for atmospheric  $CO_2$ , using the atmospheric transport model LMD<sub>2</sub> as observational operator.
- Direct flux observations.

This work was supported in part by the European Commission under contract numbers FP6-511176-2 (CarboOcean) and FP6-026188 (IMECC)

## Network Design Tool and First Applications



**Figure 3:**

The  $CO_2$  network consists of 41 Global View (GV) flask sites (+), 2 continuous measurement sites (x) and an Eddy flux measurement site (O).

Green color stands for the sites used for the network evaluation.

Red color stands for sites that are not used.

Two candidate networks are evaluated:

**Network 1 consists of 41 GV stations**

**Network 2 consists of 37 GV stations, excluding 4 sites over Europe (O)**

For further details on the Network Design Tool, contact Thomas kaminski ([Thomas.Kaminski@FastOpt.com](mailto:Thomas.Kaminski@FastOpt.com))

or consult <http://imecc.ccdas.org>

### Application to $CO_2$ fluxes

The tool has been used to evaluate candidate networks for the carbon cycle study, using only flask samples of atmospheric  $CO_2$  as observations. We focused on the  $CO_2$  fluxes. The uncertainty on the  $CO_2$  data [ $\sigma_d$ ] that reflects the combined effect of observational and model error was set to 2 ppm, for each flask.

The Uncertainties on the Net Ecosystem Production NEP (net  $CO_2$  flux between the atmosphere and the biosphere) and the Net Primary Production NPP of the biosphere are calculated for the **two networks of Figure 3**.

**Table 1:** Uncertainties on NPP and NEP evaluated from Network 1 (41 stations, green) and Network 2 (37 stations, blue). The prior uncertainties of these quantities are also reported (black).

Sigma (Gt C/yr)	parameter	Europe	Russia	Brazil
Prior uncertainties	NPP	0.66	1.08	4.86
	NEP	0.45	1.45	1.13
With inverse modelling	NPP	0.08	0.14	0.50
		0.10	0.15	0.52
	NEP	0.05	0.06	0.13
		0.06	0.07	0.13

Uncertainties on NPP and NEP decrease by more than 87% and 89% respectively, when using all the GV sites (Table 1). For the case under study, the exclusion of 4 stations does not significantly alters this reduction (i.e. less than 1%).

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